BACKGROUND

Extract from NSA Cryptolog Magazine¹:

Following World War II, little was done in the Army's airborne signal intelligence arena. Through the 1950s, ASA operators flew electronic reconnaissance missions in Navy EA-3B Sky Warriors. In the early 1960s, ASA crews again flew on board the EA-3Bs within a project called FARM TEAM. It was at this point that the Army had made a decision to invest both manpower and funds in order to have its own ability to expand its intelligence coverage of enemy forces within a theatre of operations which appeared to be increasing in both size and complexity.

Extract from the book Body of Secrets²:

Unlike the other services, the Army had paid little attention to airborne Sigint since the end of World War II. Throughout the 1950s, Army intercept operators flew missions in Navy aircraft. The codename of one of their operations in the early 1960s, also aboard a Navy Sky Warrior, seemed to sum up the problem: Farm Team. It was at that point that the Army decided to invest both manpower and funds in developing its own professional team of aerial eavesdroppers. By March 1962 the Army Security Agency had its first airborne DF platform, the RU-6A De Haviland Beaver, a single-engine aircraft that flew low and slow and had room for very few operators. Within days, intercept operators in the unit were calling it TWA: Teeny Weeny Airlines.

Extract from NSA Cryptolog Magazine³:

One veteran recalls his early days in Vietnam flying in a Caribou with an experimental system. The operators hung a long wire out the back of the aircraft for a crude direction finding antenna. Crews flew in hot, humid conditions in very loud aircraft. Missions were often four hours long, but could be longer depending on the operational tempo of the forces in contact. It has been said that air missions produced as much as one third of the intelligence known to ground forces.

¹ http://www.nsa.gov/about/cryptologic_heritage/vigilance_park/origins_of_asa.shtml
³ http://www.nsa.gov/about/cryptologic_heritage/vigilance_park/origins_of_asa.shtml
The early days of Vietnam truly marked the beginnings of Army airborne signals intelligence. The Army's U-6 Beaver was one of the first platforms converted from a utility mission to take on intelligence collection efforts from the air. As a result, it was officially redesignated as the RU-6. This, in effect, initiated the process wherein most of the remaining Army aircraft which eventually became incorporated within this emerging fleet of signals intelligence platforms, were also redesignated with a reconnaissance or "R" prefix designator.

The RU-6A aircraft was a relatively simple and basic platform equipped with on-board mission receiver equipment for homing in on signals emitted by enemy forces. The data returned were only as accurate as the pilots’ navigational skills. With no doppler/inertial navigation system (INS) or global positioning system, the pilots relied on landmarks and dead reckoning to determine their known location from which to calculate the intercepts.

Figure 1: Pathfinder with dipole antennas on horizontal stabilizers (Photo: U.S. Army)

Extract from ASA On Line⁶:

De Havilland "Beaver"

The brown, high-winged, tail-dragging airplane that would fly the mission was a De Havilland "Beaver," what the Army then called the L-20 and later designated the U-6A. This was a venerable bird. It had been serving the Army for nearly 20 years by that time. There was nothing fast or fancy about it, but it was reliable. A big radial engine with a two bladed prop would pull it along at 160 mph, top speed in a crisis. The fat fuselage was shaded by a thick, wide wing, and the wing tips were pierced by vertical rods. These were the directional antennae that would give the intelligence analyst aboard the azimuth to any radio transmitter his receiver could pick up.

In the cargo space, bent over a steel desk backed by an instrument panel, and virtually surrounded by grey steel cabinets, was a soldier wearing earphones, testing

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⁵ Ibid.
⁶ http://www.asalives.org/ASAONLINE/uwarriors.htm
his equipment and going over the collection plan for the day. The pilot settled into his seat and began his pre-flight routine. He fastened a map and the collection plan to a clipboard mounted above instruments in front of him, shouted "clear"—to no one in particular—out the window, and turned the switch.

The pilot kept a constant check on his position by reference to the map in front and the ground below. Abruptly, he kicked the right rudder and the plane swung around to the north like a weathervane in a strong gust. The soldier-technician had picked up one of the wanted call-signs and the pilot had turned the airplane’s nose around until the instruments told them that he was flying directly toward the transmitter. Checking his position with reference to the terrain below, he marked a dot on the map, noted the airplane’s heading with a glance at the compass and, with a protractor, drew the azimuth to the transmitter. He worked fast, flying the Beaver with his feet.

That accomplished, the next task was to fly as fast as the old bird would take him to another part of the sky to get another bearing before the transmitter fell silent. With the throttle to the firewall, he banked in a tight turn and headed southeast. They were lucky that morning, for this transmitter had a long message to send. Through the combined skills of the pilot and the technician, they managed three bearings. Where the bearings intersected was a “fix” the location of an enemy transmitter belonging to a known enemy unit.

Unfortunately, the equipment then in the hands of the RRU denied them the capability to "fix" with precision. Error was built into the system and the size of the error depended on the relative skills and experience of the pilots, operators and analysts, and the accuracy to which the equipment was calibrated. Nevertheless, correlated with intelligence gained from prisoners-of-war, captured documents, and agents, ARDF intelligence became the best means for following enemy movement. From his movements, intelligence officers and commanders could estimate the enemy’s intentions.
Extract from the book *The Most Secret War*:

The ARDF system consisted of two dipole antennas on the leading edge of each wing connected by cable to a Receiver Radio R–390 housed in the fuselage. Instead of having an antenna within the plane, the aircraft itself acted as the direction finder. By flying with the plane’s wings and antennas at right angles towards the transmitter, the pilot allowed the operator to take a series of bearings that resulted in a fix. The operator’s success depended upon the pilot’s ability to keep the aircraft pointed at the target while reading his gyrocompass. In areas without prominent features, such as over dense vegetation, the pilot had to deploy at a greater than usual distance from the target to obtain a recognizable reference point.

*Figure 4: ARDF System*[^8]

*Figure 5: Flying pattern*[^9]

[^8]: Ibid.
[^9]: Ibid.
The single-engine companion Army platform, the RU-1 Otter, was similarly configured with personnel and equipment, but it was an expanded platform. But it wasn’t until the introduction of the Army’s RU-8D Seminole that a significant advance was made in the SEMA fleet and in the contribution these intelligence platforms were providing the theatre tactical commanders. In addition to having on-board mission equipment similar to that found initially on both the RU-6A and the RU-1A, the RU-8D aircraft were equipped with the Marconi doppler navigation system. This required the co-pilot to manually plot the ARDF fixes (locations) to large pads of graph paper on his lap. (Masking tape was applied to the aircraft doors to prevent the plotting sheets from being sucked out of the aircraft.) Also, the RU-8Ds were equipped with blade antennas in the wings, which gave them the capability to home in on a transmitter and fly a standard flight pattern to achieve the geometry necessary to obtain several lines of bearing (LOB).
ANNEX H To
The Story of 547 Sig Tp
in SVN 1966-1972

Figure 7: RU-1A Otter (Photo: U.S. Army)\textsuperscript{11}

Figure 8: RU-1A Otter airborne collection platform\textsuperscript{12}


\textsuperscript{12} The Most Secret War Army Signals intelligence in Vietnam: James L Gilbert, Military History Office, US Army Intelligence and Security Command, Fort Belvoir, Virginia
Beechcraft RU-8\textsuperscript{13}

The RU-8Ds had greater range and speed and were equipped with Doppler radar to allow all-weather operations. But, like everything else in Vietnam things did not work out as expected. The radar system required continuous maintenance due to the heat and humidity, and if it failed during a mission, the low wings made it difficult to manually mark a location on the map. The aircraft was equipped with the new AN/ARD-15\textsuperscript{14} which offered a sharper null and a better determination of the median null. However, the cockpit located above the wings was more exposed to the sun and space for the ARDF operator, located behind the pilot, was more cramped.\textsuperscript{15}

![Figure 9: AN/ARD-15 mount in the RU-8D\textsuperscript{16}](image-url)

\textsuperscript{13} http://www.globalsecurity.org/military/systems/aircraft/u-8.htm The Beechcraft Queen Air is in military service as the U-8F Seminole both as an executive aircraft and a feeder liner. A model used by the US Army is the B-80. During the Vietnam war the Army employed signals intelligence collection systems mounted in RU-8 Seminole aircraft. The wings are low-mounted and unequally tapered with blunt tips, featuring wide wing roots and positive slant. Two piston engines are mounted in and extending beyond the wings' leading edges. The fuselage is short, thick, round, and tapered to rear section. The tapered nose features a stepped cockpit. The tapered tail flats have blunt tips and high-mounted on body with positive slant. The swept-back tail fin has a square tip.

\textsuperscript{14}http://www.designation-systems.net/usmilav/jetds/an ard2arm.html"CEFISH PERSON"/"WINE BOTTLE"/"CHECKMATE"/"SEVEN SISTERS" HF Direction Finding System; used in RU-6A, RU-8D


Figure 10: Beechcraft Seminole RU-8 (early model)

Figure 11: Beechcraft Seminole RU-8 (later model)
Extract from Armchair General Web Page:\(^\text{17}\)

![Image of RU-8 in flight](http://www.armchairgeneral.com/forums/showthread.php?t=65809&page=3)

Figure 12: RU-8 in flight

The RU-8D carried a crew of three (pilot, co-pilot and mission operator T/O). Its purpose was one of airborne radio direction finding (ARDF). The mission equipment configuration (initially code named – Winebottle) consisted of two Collins general coverage HF receivers installed at an operators position in the rear, one external HF intercept antenna (wire from fuselage to vertical stabilizer), a set of wires joining the wing-tips to the tail feathers (for the purpose of bonding and antenna counterpois), an AN/ASN-64 Doppler Navigation system (Marconi), a C-12 Digital flux gate compass system and an HF/DF antennas system consisting of an Adcock configured set of helically wound, capacitively loaded, vertical mounted (through the wings) dipoles at the wing-tips.

The system worked like this - The operator would search for/find an HF station to DF (CW [Continuous Wave Morse code] tactical intercepts). Upon finding a station, the operator would switch to the DF antenna and patch the received audio to the pilot’s intercom.

The pilot would then turn the aircraft until an audio null (point where signal disappeared) was detected in signal strength, while keeping the wings absolutely level on the null bearing.

The co-pilot (acting as a plotter) would then record the Doppler geographic coordinates for that bearing shot. The pilot would then make a turn somewhat perpendicular to the null bearing and fly on for a short distance (period of time).

When it was estimated that sufficient distance had been covered, the pilot would turn again back towards the station and make another null shot. Coordinates and bearings would be recorded again and the process would continue in this fashion.

(usually five or six bearings could be taken prior to the station going off the air) until enough shots existed to record the plotted positions and bearings on a special plotting sheet.

The results would be a succession of aircraft positions plotted around a central point established by the crossing of the numerous bearing lines from the aircraft positions. The plotting sheet coordinates then established (accuracy of about 100 meters – if you were good and other conditions allowed) the geographic position of the transmitting station.

If intelligence indicated that the station was associated with a high priority target (these targets would be briefed prior to the mission), then the position would be relayed over a secure (KY-28) FM communications link to waiting or available B-52 bombers (Milky). They would arc-light (saturation bomb) the area as soon as we could be clear. --Roger Brown, former RU-8D pilot.

Although overflight of the actual target sometimes occurred, the procedure for flying the pattern for triangulating the target tried to prevent overflight whenever possible. Additionally, some of the aircraft were configured with radio fingerprinting to further enhance signal identification. The mission gear on board these RU-8D aircraft were known by the nicknames WINEBOTTLE, CEFISH PERSON, and CHECKMATE. These aircraft, with the on-board systems and crews, truly became the new workhorse of the Army's SEMA fleet primarily due to a combination of the improved mission gear and a newly introduced multi-engine capability, each contributing to expanding and improving the unit's mission coverage in several dimensions.

Figure 13: Interior of RU8

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18 Photograph courtesy of Garth Brown
RU-21

In 1968, a project known as LAFFIN EAGLE entered service with the Army and within Vietnam. It used the Army RU-21 aircraft with additionally improved mission gear to include an automated direction finding capability as a result of the use of an on-board inertial navigation system.

![Figure 14: RU-21](http://www.armysignalocs.com/veteranssalultes/sigint.html)

![Figure 15: RU-21D](http://www.armysignalocs.com/veteranssalultes/sigint.html)

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With the follow-on introduction of three JU-21 LEFT JAB into Vietnam, the Army now had the first airborne collection system to give 360-degree direction finding coverage. It was also the first system to use a digital computer to store calibration tables for the DF system and to calculate emitter locations from the LOBs generated by the "Spaced Loop" DF antenna and aircraft position data furnished by the on-board INS. In essence, what the RU-6A, the RU-1A, and, most importantly, the RU-8D had provided and accomplished as the Army's initial trio of signals intelligence platforms was now resident in the proliferating fleet of RU-21s in both Vietnam and CONUS.

Finally, a truly special unit was formed and deployed to Vietnam using Army pilots, Army ASA mission operators on board a Navy P-2V Neptune four-engine aircraft. This Army project was a significant leap in both mission coverage and overall mission capability. As with most of the other platforms, these aircraft were redesignated specifically as RP-2E aircraft with an associated mission project name of CEFLIEN LION or CRAZY CAT.

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Left Bank

The remaining platforms which also contributed to the Army's airborne signal intelligence capability were six specially configured UH-1 helicopters. These aircraft were redesignated as EH-1 LEFT BANK aircraft and were assigned directly to the tactical war-fighting divisions in Vietnam. These LEFT BANK assets were manned and maintained by ASA operators, also found with the same divisions. Their flight profiles included both high- and extremely low-altitude operating envelopes necessary to locate and target tactically oriented enemy threats of immediate and times-sensitive value.

Extract from Armchair General Webpage

Project Left Bank was a unique airborne SIGINT collection method used by two Radio Research Direct Support Units (DSUs), the 371st RR Co (supporting the 1st Cavalry Division) and the 374th RR Co (supporting the 4th Infantry Division. It was unique in the sense that it utilized the venerable Huey helicopter platform (specifically a UH-1D). Very much a collaborative effort, its air crews were contributed by the supported unit, while operators were from the RR DSU. Originally it was intended as a multi-collection system, including an AN/ARQ-27 DF system, an RO-278 radio finger-printing (RFP) position, and a voice recorder. This was eventually reduced to a pure ARDF mission, since the RFP equipment was producing too many false readings due to the aircraft’s vibration.

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Figure 18: Left Bank equipment

Figure 19: Left Bank in flight
Figure 20: Left Bank Operator\textsuperscript{23}

Extract from the book \textit{Unlikely Warriors}\textsuperscript{24}:

\begin{quote}
The Army Security Agency’s Secret War in Vietnam 1961-1973: What made Left Bank so successful was the combining of the DF platform with the firepower and mobility of airborne warfare. If the Left Bank pilot located a “fix,” he hovered over the area at canopy level looking for evidence of troop movement or enemy installations; if he spotted enemy personnel, he called in an Arc Light mission (B-52s), gunships, or troops. During January 1969, Left Bank was responsible for six B-52 strikes, multiple artillery rounds, and troop insertions that resulted in over 300 enemy KIA. Lt. Col. Donald E. Grant, C.O. of the 303rd RR Bn said, “Left Bank went out, obtained a target, and then became a small command center in the sky directing the attack. In fact, the Cav became so reliant on this technique that when the Left Bank was no longer available their effectiveness was severely hampered.”
\end{quote}

\textbf{Staff Expectations}

Often, the ultimate customers for the information did not understand the capabilities of the systems. They expected to be able to go to a given location and find the enemy at that location speaking on the radio. There were some constraints with the systems, in that the location of the target could be depicted as an elliptical core - not a pinpoint target. Therefore, the emitter was not always exactly where the report indicated.


\textsuperscript{24} Ibid.
Aircraft Signature

All of the US Army ARDF platforms were very distinguishable due to the array of antennas on the aircraft.
US ARMY ARDF PROCEDURE

Crew

The crew of each aircraft consisted of a command pilot, a co-pilot and an ARDF operator in the rear compartment.

Pre Mission Brief

Before flying a mission the crew were issued with a ‘Frag Point’\(^{25}\), a target list that contained target identities, schedule times, frequencies, callsigns, last location (if known) and the relevant Direct Support Unit (DSU)\(^{26}\) contact frequencies.

Aircraft Operation

Most of the US Army ARDF aircraft would normally fly between 2000 and 5000 feet above ground level and for best results operate approximately three to ten kilometres from a target. Depending on the type of aircraft, a mission would last approximately three hours.

DF Operation

During a mission the following procedures were taken:

- **Arrival at Target Area.** When the aircraft arrived in the specified area, the ARDF operator would immediately commence searching for targets and make contact with the DSU.

- **Acquisition of a Target.** When the operator acquired a target, he patched the audio from the DF receiver to the pilot’s headphones.

- **Rotation of Aircraft.** When the pilot heard the signal in his headphones, he turned the aircraft towards the suspected location of the transmitter until such time as he received an audio null in his headphones.

- **Confirmation of Signal.** After getting the first null, the pilot put the aircraft into a flat left-right-left “skid” to confirm the null. When the null was confirmed, the pilot would call “Mark”.

- **Aircraft Position.** When the co-pilot heard ‘mark’ he would note the aircraft heading and Doppler\(^{27}\) reading and record both on a plotting chart.

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\(^{25}\) **Frag Point** in ARDF context is the central location of where an aircraft is to operate.

\(^{26}\) **Direct Support Unit (DSU).** The term DSU was given to the Sigint unit that was on the ground in the aircraft’s tasking area. The DSU passed additional technical information up to the aircraft when required and received all Fix reports from the aircraft for action and on-forwarding.

\(^{27}\) **Doppler (navigation)** Dead reckoning performed automatically by a device which gives a continuous indication of position by integrating the speed and the crab angle of the aircraft as derived from measurement of the Doppler effect of echoes from directed beams of radiant energy transmitted from the craft.
Data Processing

- **LOB.** The plot would show a LOB from the aircraft.

- **Additional LOBs.** After the co-pilot has computed the first LOB, the pilot would then turn at right angles to the target, fly for an unspecified period, then repeat the exercise. Normally, about six LOBs would be taken on each target. The number of LOBs taken would depend on how long the target was active.

- **FIX.** When the co-pilot plotted all the LOBs he would be able to determine a Fix with a circular area of probability (accuracy)^28.

- **Reporting.** The result would be transmitted to the DSU via one time pad and later secure radio.

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**Example of a US Army ARDF Plot**

![Example of a US Army ARDF Plot](image)

**Target Transmitter**

**US ARMY FIX**

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**Target Activity**

The VC/NVA were well aware that the US Army flew ARDF aircraft and over time became used to the noise of the ARDF aircraft as they seemed to always appear when they were

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28 **CEP.** A Circular error of probability is an intuitive measure of a system’s precision. In DF terms it is the approximate average distance between a centre point and the intersecting lines (LOBs).
transmitting. As a consequence, whenever they heard the aircraft, they would stop transmitting. To keep the target transmitting the aircraft would normally attempt to stand off at greater distances from the target. This in turn increased the circle of error.

547 Sig Tp Support

Throughout its deployment, 547 Sig Tp was supported by the 146th Aviation Company.

146 Avn Co Location

Originally the Company was located at Tan Son Nhut Airport, Saigon, and later moved to Long Thanh just to the north of Phuoc Tuy Province.

A close relationship was established between the 146th and 547 SigTp, and this continued throughout the deployment.

In early 1970 a brief exchange program of ARDF pilots was established between pilots from 161 Recce Flt and 146 Avn Co.
Figure 21: 146 Avn Co History²⁹